**TEMPORARY REVISION NO. 019**
**To: EA500 POH and FAA-Approved Airplane Flight Manual**

**Magnetic Compass**

This Temporary Revision affects the AFM Part Number 06-122204, Revision 04, dated July 23, 2012. Remove this TR when Revision 05 is inserted. Record this TR insertion (or removal) on the Log of Temporary Revisions.

**Insert this page facing LOTR-2.**

06-122204-TR019

Signature: Ronald D McClung Date: MAR 06 2013

FOR Steven L. Lardonois
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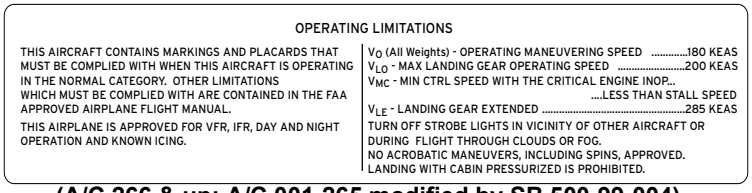
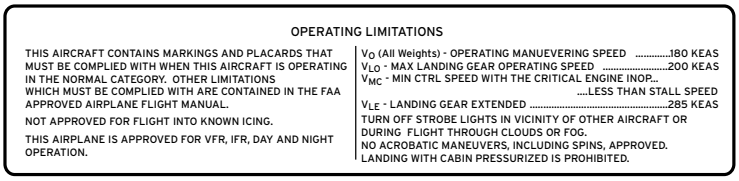
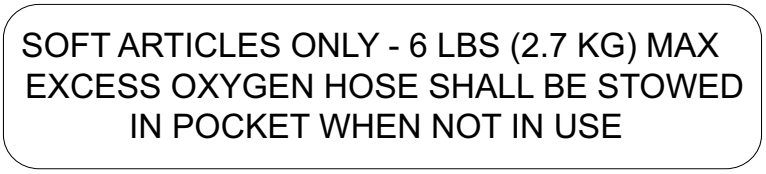



**(A/C 266 & up; A/C 001-265 modified by SB 500-99-004)**




**(A/C 001-265 not modified by SB 500-99-004)**

**Figure 1-1. Cockpit, Left and Right Sidewall**




**OR**

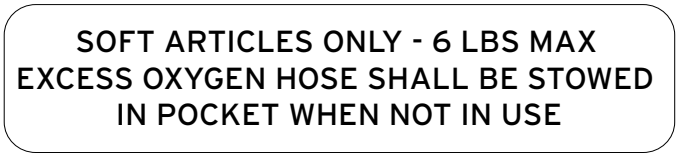



**Figure 1-2. Cockpit, Left and Right Lower Sidewall**

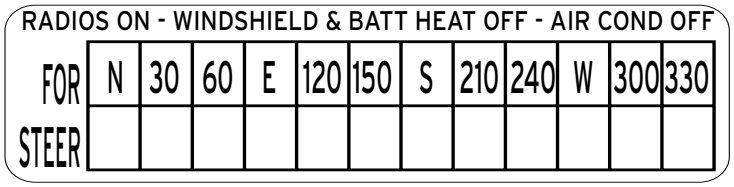



**Figure 1-3. Cockpit, Adjacent to Compass (If Installed)**

## ALTITUDE DISAGREE


Altitude Data disagrees between Air Data Computers 1 and 2.

1. Left and Right Altitude Data .....Compare with MFD (ADC 3) Altitude
2. ADC PFD (SETUP SENSOR Page) ..... Select Valid ADC
3. RVSM equipment requirements no longer met. Advise ATC.

**NOTES**

- Autopilot will disconnect and cannot be reconnected.
- ADC 3 airspeed can be corrected using *Airspeed Calibration - ADC 3* in Section 5, "Performance."

## ATT (on PFD or MFD)


(A/C with NG 1.5)


(A/C without NG 1.5)

Attitude data is not available for display. Message is displayed on the PFD or MFD attitude display area.

1. Reference MFD or opposite display if a valid source is available.
2. RVSM equipment requirements no longer met. Advise ATC.

***If a valid source is available:***

1. AHRS PFD (SETUP SENSOR page).....Select Valid AHRS

   Or

1. Reference MFD (ATT3) if installed.

***If an attitude source is not available:***

1. Use airspeed, altitude, vertical speed, magnetic compass (if installed) and any other available data to control aircraft. If possible, exit and avoid flight in IMC conditions.

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## HDG (on PFD or MFD)


A/C with NG 1.5


AC without NG 1.5

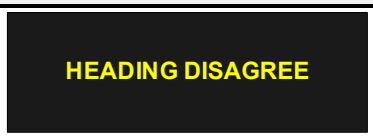
Heading data is not available for display. Message is displayed on the PFD or MFD heading display area.

1. Reference magnetic compass (if installed) or opposite display.

***If a valid AHRS source is available:***

1. AHRS PFD (SETUP SENSOR page) ..... Select valid AHRS

## HEADING DISAGREE





Heading disagrees between Attitude Heading Reference Systems 1 and 2.

1. Compare left and right headings with all available sources and magnetic compass (if installed).
2. AHRS PFD (SETUP SENSOR Page) ..... Select Valid AHRS

--- END ---

The optional third Attitude sensor does not provide heading data. Instead, a traditional whisky compass (if installed) is installed on the instrument panel left of the pilot's PFD together with a compass correction card.

A separate information processor within the AHRS unit collects, combines if necessary and distributes information from the ADC, AHRS and GPS to the ACSs, FADECs, Autoflight system, and pilot displays.

### *Controls and Indications*

The Attitude Indicator (AI) is located in the upper center portion of the PFD. It uses a traditional blue sky/brown ground with a horizon line extending the width of the display. The AI also contains a pitch ladder, a roll angle pointer/scale and a yellow wedge style attitude reference symbol. Flanking the attitude reference symbol are two yellow horizon reference pointers.


**Figure 7-36. Attitude Indicator**

*Pitch*

The AI is accurate for ± 90° of pitch. The pitch display remains static over the range of 23° nose up to 23° nose down. Beyond ± 23° a portion of the sky or a portion of the ground are always visible. At extreme pitch angles, a series of red chevrons point towards the horizon.

The pitch scale is displayed with horizontal labeled lines at 10°, 20°, 30°, 40°, 50°, and 70°, with unlabeled lines every 2.5° up to 30° and every 5° from there to 50°.

*Roll*

The AI is accurate for ± 180° of roll. The roll scale is displayed with a white triangle at 0°, large tick marks at 30° and 60° left and right; and smaller tick marks at 10°, 20° and 45° left and right. Roll angle

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